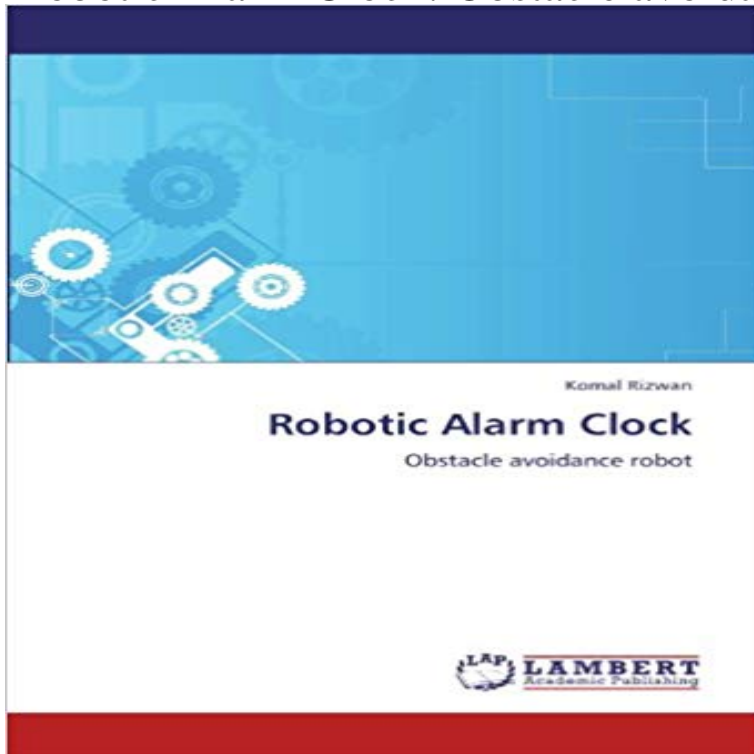


Robotic Alarm Clock: Obstacle avoidance robot



The manuscript details the research and development of a Robotic Alarm Clock. Proposed in this book is a system that is designed to move randomly and avoid the obstacles encountered during its random motion. The sensors detect the obstacles and guide the robot to avoid collision and choose a wise path. It is a smart machine and is self-driven with the help of a chargeable battery which is provided with the robot assembly. The alarm clock is then used as a trigger to the robot. The sole purpose of this project was to introduce an entirely new concept by merging the modern concept of robotics with time piece. The project focuses the need of deep sleepers. This Robotic Alarm Clock will help them to wake up, and not giving them a sole chance to sleep through the alarm. The clock has a smart ability to run aimlessly in the room as the alarm starts ringing.

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